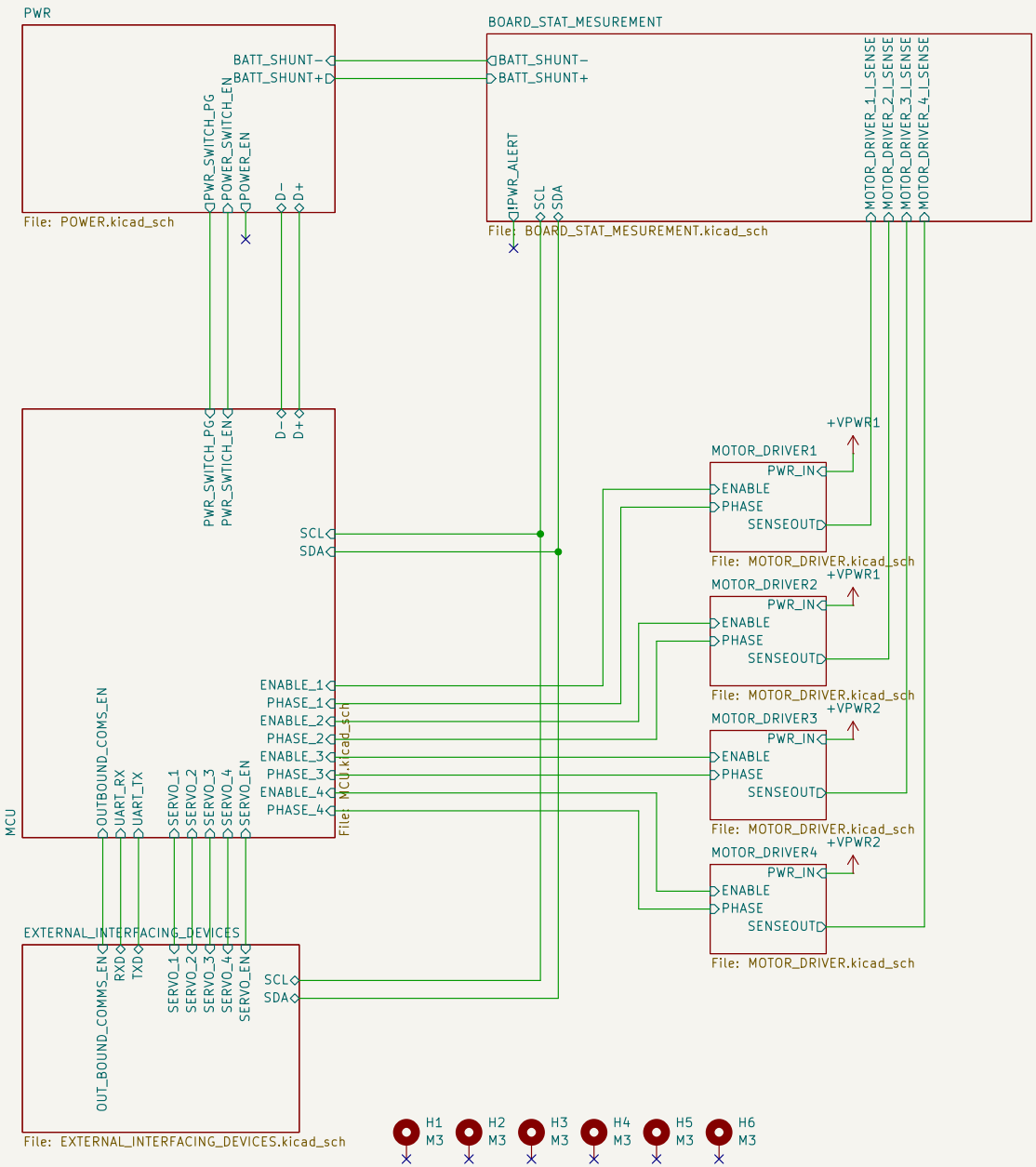
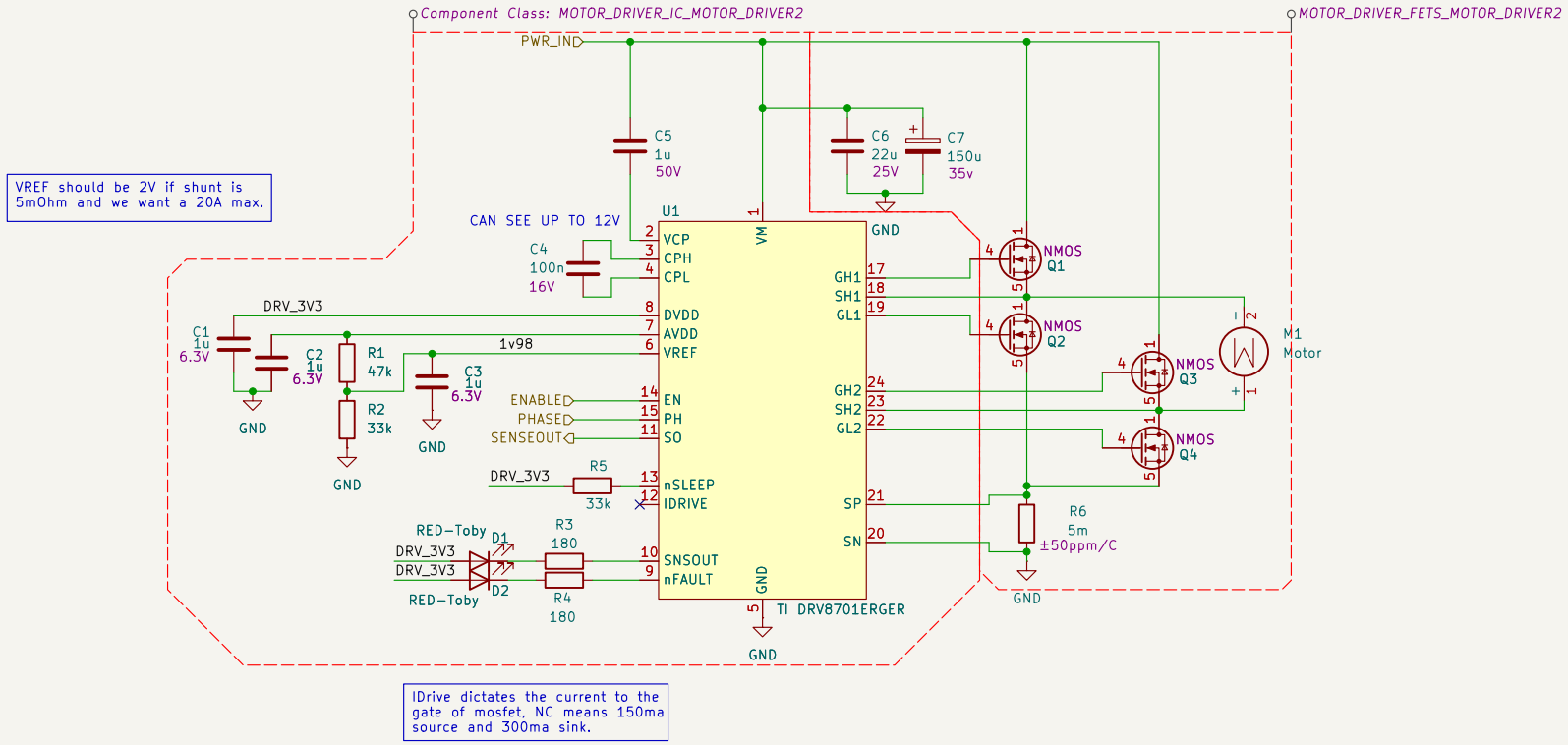


CHANGE LOG

Sheet: /		
File: esp32-racer.kicad_sch		
Title:		
Size: A4	Date:	**Rev:**
KiCad E.D.A. 10.0.0		Id: 1/10


Component Class: MOTOR_DRIVER_IC_MOTOR_DRIVER2
MOTOR_DRIVER_FETS_MOTOR_DRIVER2
VREF should be 2V if shunt is 5mOhm and we want a 20A max.
PWR_IND
C5
1u
50V
C6
22u
25V
C7
150u
35v
CAN SEE UP TO 12V
U1
C4
100n
16V
VCP
CPH
CPL
VM
GND
GH1
SH1
GL1
NMOS
Q1
NMOS
Q2
NMOS
Q3
NMOS
Q4
M1
Motor
DRV_3V3
C1
1u
6.3V
C2
1u
6.3V
R1
47k
R2
33k
1v98
C3
1u
6.3V
DVDD
AVDD
VREF
ENABLE
PHASE
SENSEOUT
EN
PH
SO
GH2
SH2
GL2
DRV_3V3
R5
33k
nSLEEP
IDRIVE
SP
SN
R6
5m
±50ppm/C
RED-Toby
D1
D2
R3
180
R4
180
SNSOUT
nFAULT
TI DRV8701ERGER
IDrive dictates the current to the gate of mosfet, NC means 150ma source and 300ma sink.
Sheet: /MOTOR_DRIVER2/
File: MOTOR_DRIVER.kicad_sch
Title:
Size: A4
Date:
Rev:
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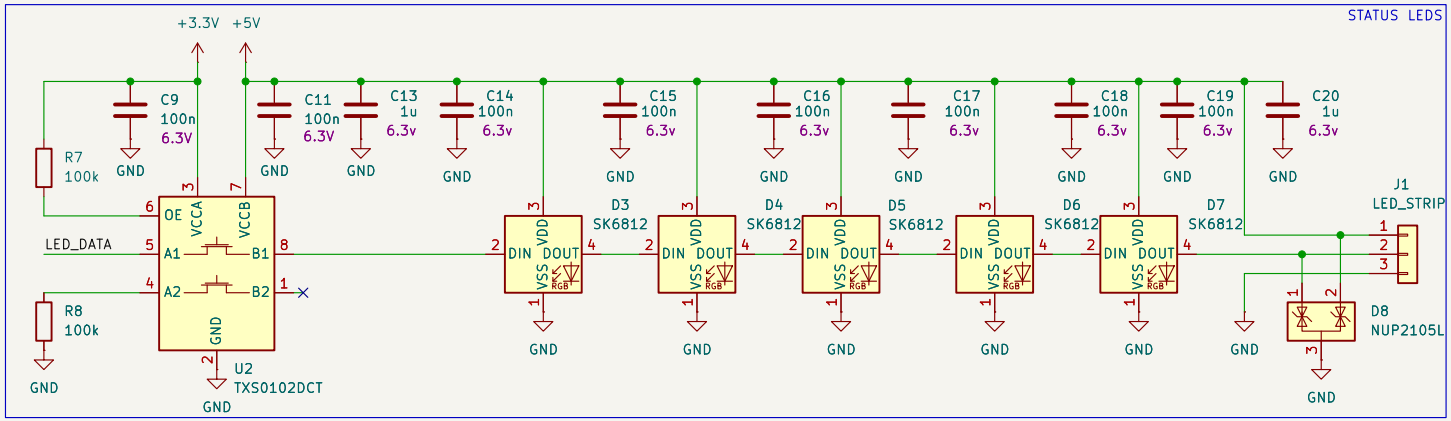

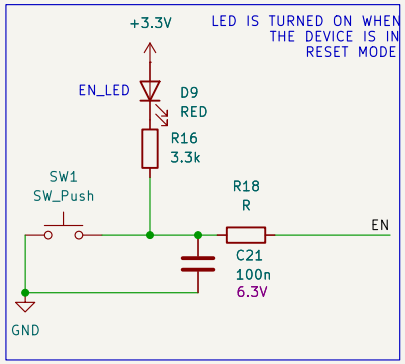

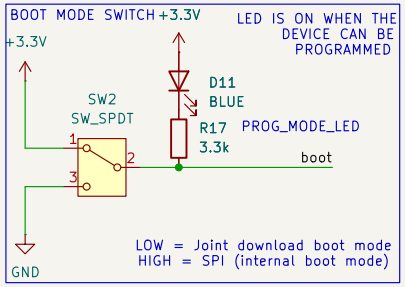

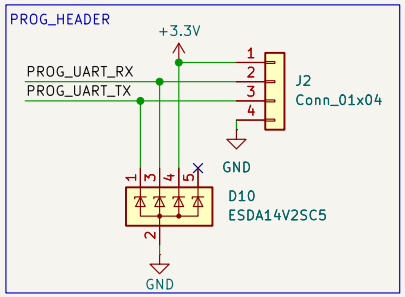

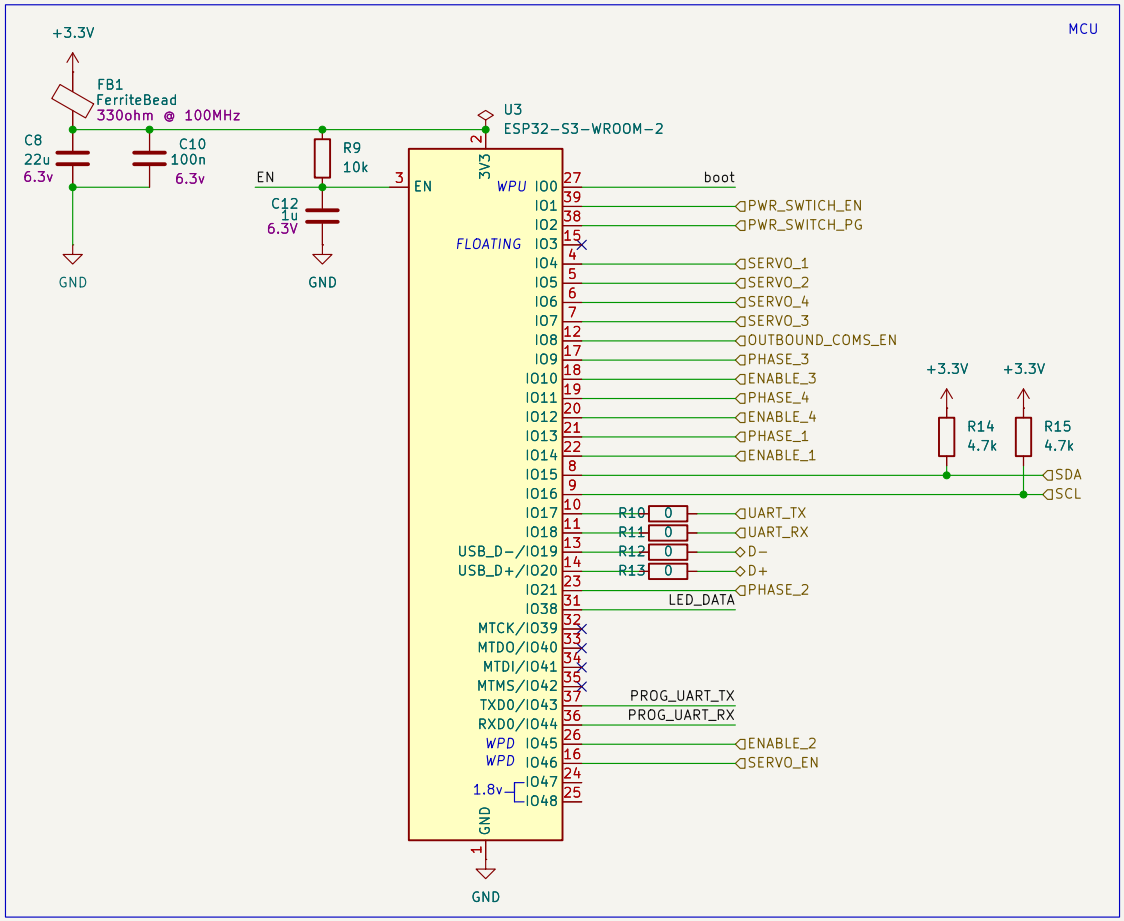

Sheet: /MCU/		
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Title:		
Size: A4	Date:	**Rev:**
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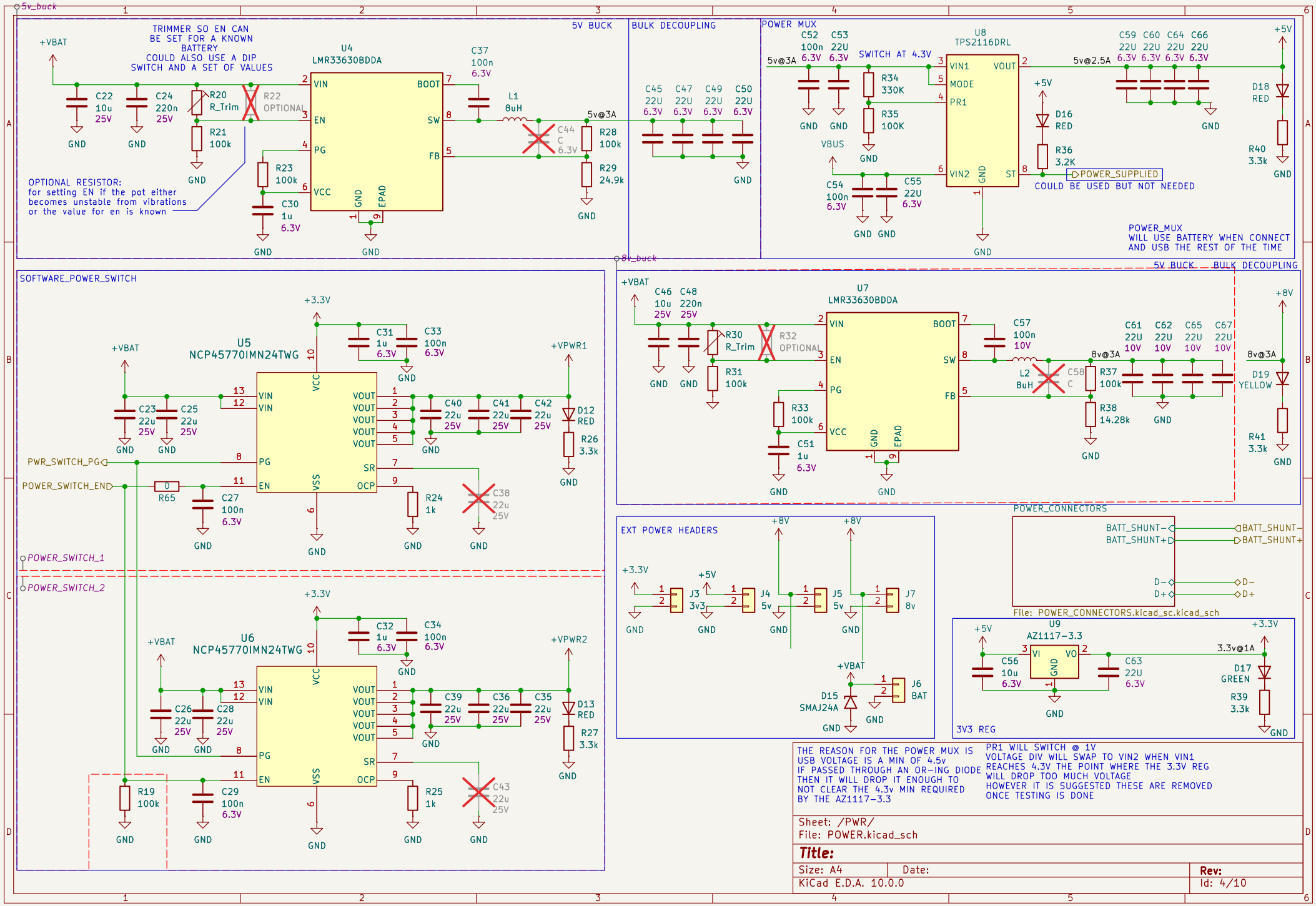
5v_buck
5V BUCK
BULK DECOUPLING
POWER MUX
TRIMMER SO EN CAN BE SET FOR A KNOWN BATTERY
COULD ALSO USE A DIP SWITCH AND A SET OF VALUES
+VBAT
U4
LMR33630BDDA
C22 10u 25V
C24 220n 25V
R20 R_Trim
R22 OPTIONAL
R21 100k
R23 100k
C30 1u 6.3V
C37 100n 6.3V
L1 8uH
C44 C 6.3V
R28 100k
R29 24.9k
5v@3A
C45 C47 C49 C50 22U 6.3V
OPTIONAL RESISTOR:
for setting EN if the pot either becomes unstable from vibrations or the value for en is known
U8
TPS2116DRL
C52 100n 6.3V
C53 22U 6.3V
5v@3A
SWITCH AT 4.3V
R34 330K
R35 100K
VBUS
C54 100n 6.3V
C55 22U 6.3V
C59 C60 C64 C66 22U 6.3V
5v@2.5A
+5V
D16 RED
R36 3.2K
D18 RED
R40 3.3k
POWER_SUPPLIED
COULD BE USED BUT NOT NEEDED
POWER_MUX
WILL USE BATTERY WHEN CONNECT AND USB THE REST OF THE TIME
8v_buck
5V BUCK
BULK DECOUPLING
U7
LMR33630BDDA
C46 10u 25V
C48 220n 25V
R30 R_Trim
R32 OPTIONAL
R31 100k
R33 100k
C51 1u 6.3V
C57 100n 10V
L2 8uH
C58 C
R37 100k
R38 14.28k
8v@3A
C61 C62 C65 C67 22U 10V
D19 YELLOW
R41 3.3k
8v@3A
SOFTWARE_POWER_SWITCH
U5
NCP45770IMN24TWG
+3.3V
C31 1u 6.3V
C33 100n 6.3V
+VPWR1
C23 22u 25V
C25 22u 25V
C40 22u 25V
C41 22u 25V
C42 22u 25V
D12 RED
R26 3.3k
PWR_SWITCH_PG
POWER_SWITCH_EN
R65 0
C27 100n 6.3V
R24 1k
C38 22u 25V
POWER_SWITCH_1
POWER_SWITCH_2
U6
NCP45770IMN24TWG
C32 1u 6.3V
C34 100n 6.3V
+VPWR2
C26 22u 25V
C28 22u 25V
C39 22u 25V
C36 22u 25V
C35 22u 25V
D13 RED
R27 3.3k
R19 100k
C29 100n 6.3V
R25 1k
C43 22u 25V
EXT POWER HEADERS
J3 3v3
J4 5v
J5 5v
J7 8v
J6 BAT
D15 SMAJ24A
POWER_CONNECTORS
BATT_SHUNT-
BATT_SHUNT+
D-
D+
File: POWER_CONNECTORS.kicad_sc.kicad_sch
U9
AZ1117-3.3
C56 10u 6.3V
C63 22U 6.3V
3.3v@1A
D17 GREEN
R39 3.3k
3V3 REG
THE REASON FOR THE POWER MUX IS USB VOLTAGE IS A MIN OF 4.5v IF PASSED THROUGH AN OR-ING DIODE THEN IT WILL DROP IT ENOUGH TO NOT CLEAR THE 4.3v MIN REQUIRED BY THE AZ1117-3.3
PR1 WILL SWITCH @ 1V
VOLTAGE DIV WILL SWAP TO VIN2 WHEN VIN1 REACHES 4.3V THE POINT WHERE THE 3.3V REG WILL DROP TOO MUCH VOLTAGE
HOWEVER IT IS SUGGESTED THESE ARE REMOVED ONCE TESTING IS DONE
Sheet: /PWR/
File: POWER.kicad_sch
Title:
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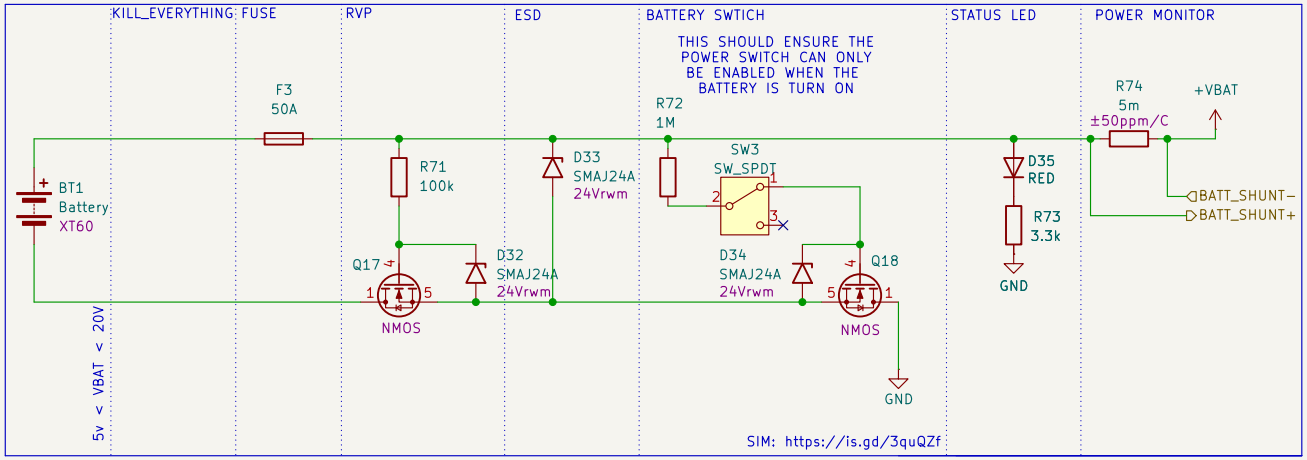
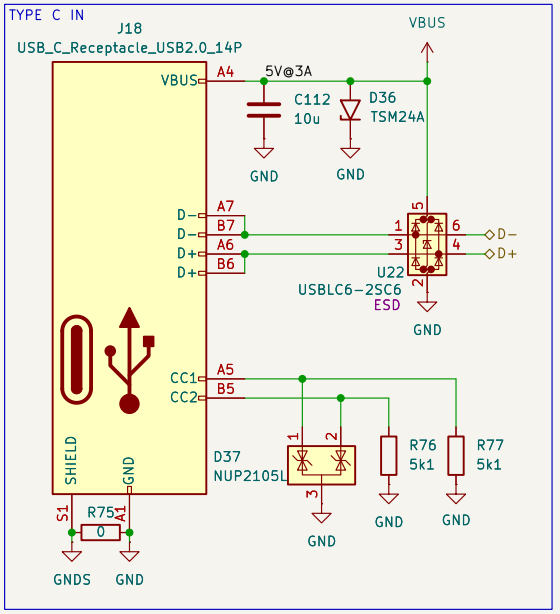
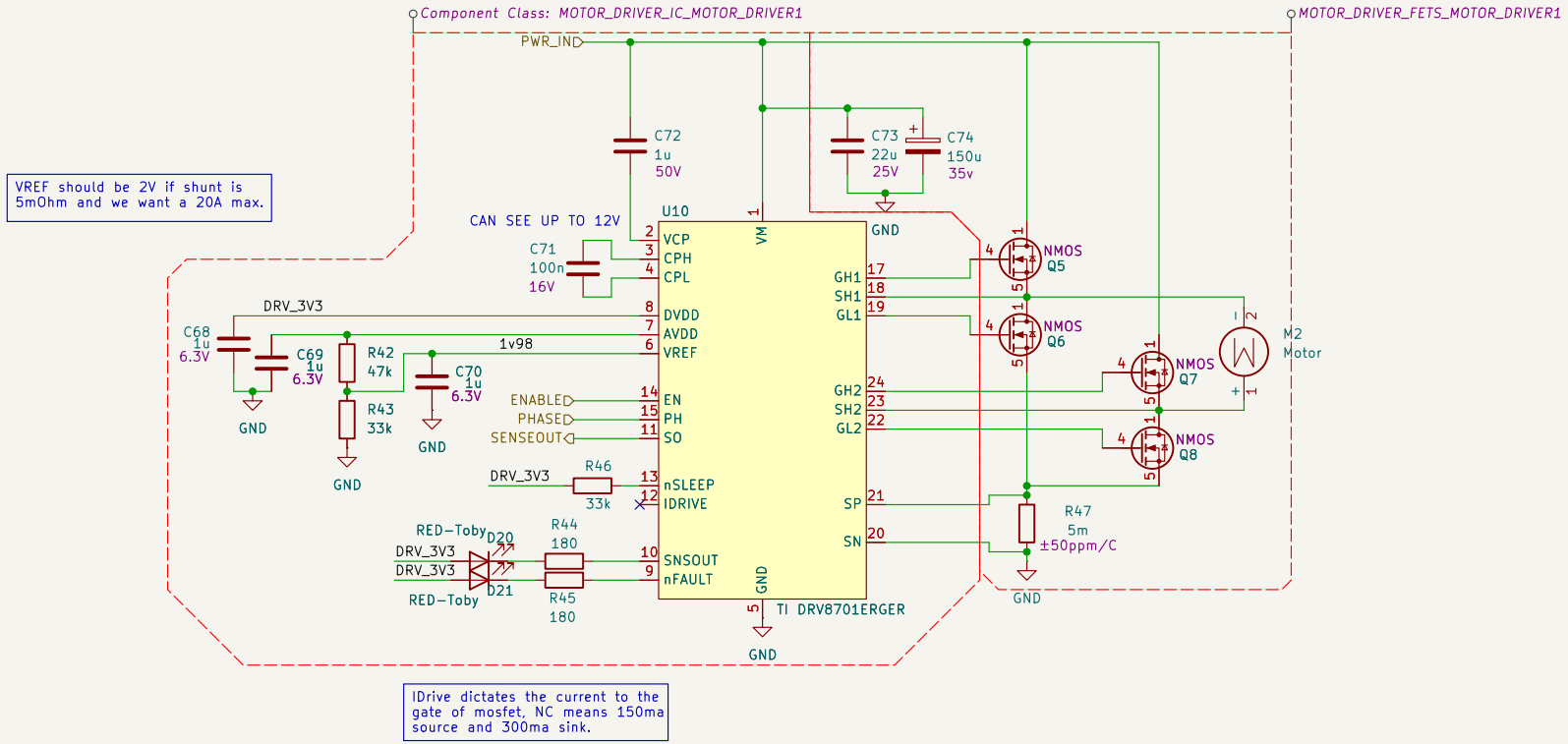




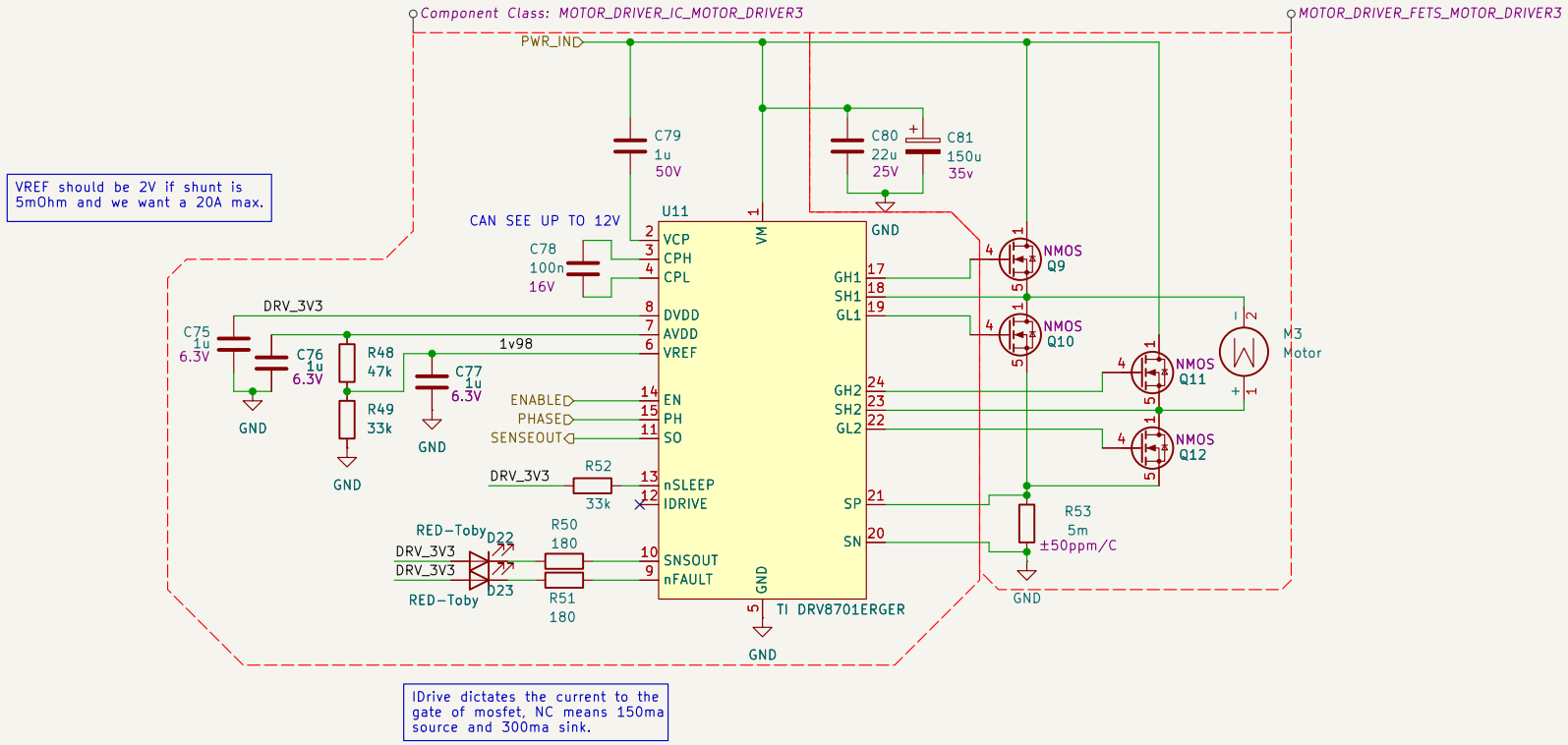
Sheet: /PWR/POWER_CONNECTORS/		
File: POWER_CONNECTORS.kicad_sc.kicad_sch		
Title:		
Size: A4	Date:	**Rev:**
KiCad E.D.A. 10.0.0		Id: 10/10

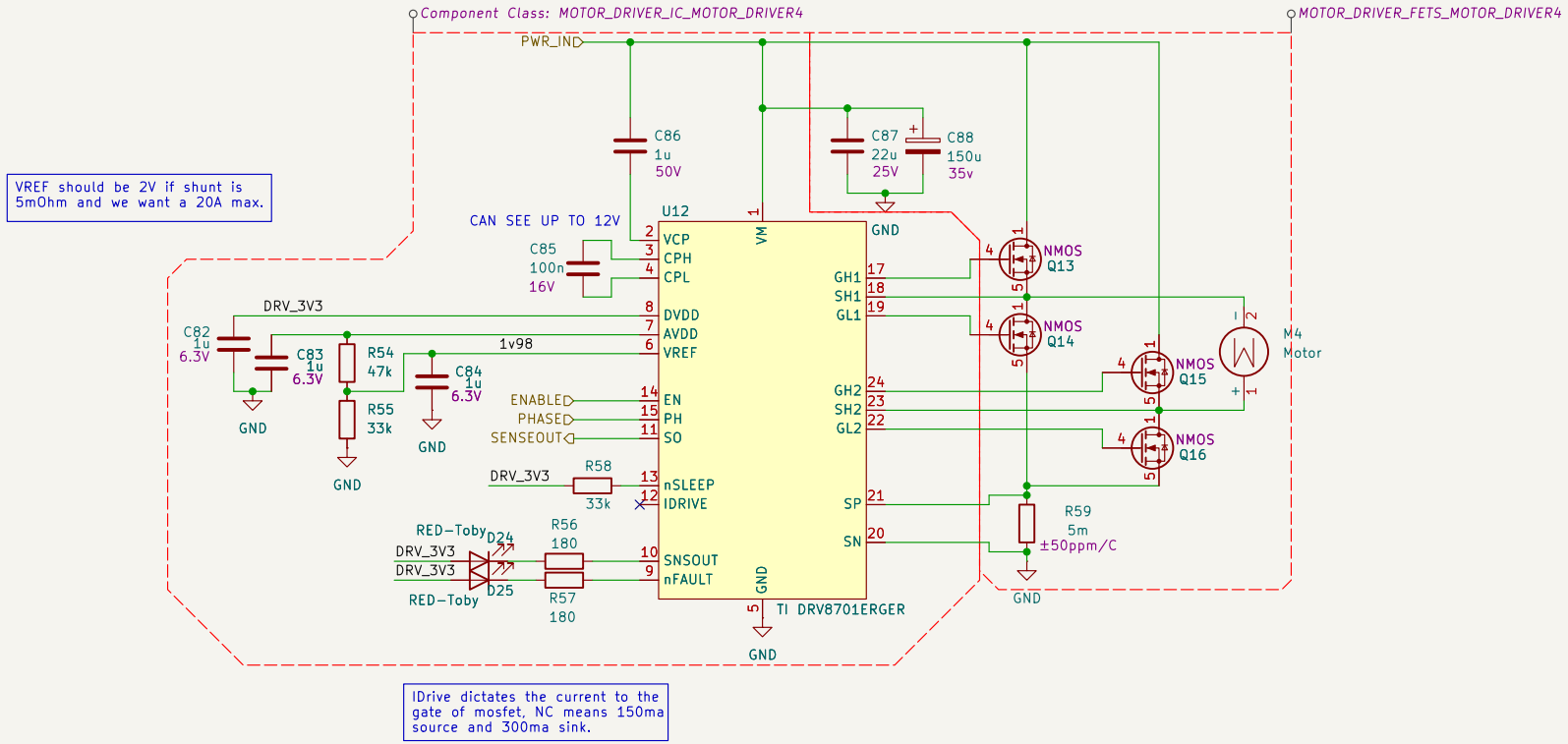


Sheet: /MOTOR_DRIVER1/
File: MOTOR_DRIVER.kicad_sch

Title:

Size: A4 | Date: | **Rev:**
KiCad E.D.A. 10.0.0 | Id: 5/10


Component Class: MOTOR_DRIVER_IC_MOTOR_DRIVER3
MOTOR_DRIVER_FETS_MOTOR_DRIVER3
VREF should be 2V if shunt is 5mOhm and we want a 20A max.
PWR_IND
C79 1u 50V
C80 22u 25V
C81 150u 35v
CAN SEE UP TO 12V
U11
C78 100n 16V
VCP
CPH
CPL
VM
GND
GH1
SH1
GL1
NMOS Q9
NMOS Q10
NMOS Q11
NMOS Q12
M3 Motor
DRV_3V3
C75 1u 6.3V
C76 1u 6.3V
R48 47k
R49 33k
1v98
C77 1u 6.3V
DVDD
AVDD
VREF
ENABLE
PHASE
SENSEOUT
EN
PH
SO
GH2
SH2
GL2
R52 33k
nSLEEP
IDRIVE
SP
SN
R53 5m ±50ppm/C
RED-Toby
D22
D23
R50 180
R51 180
SNSOUT
nFAULT
TI DRV8701ERGER
IDrive dictates the current to the gate of mosfet, NC means 150ma source and 300ma sink.
Sheet: /MOTOR_DRIVER3/
File: MOTOR_DRIVER.kicad_sch
Title:
Size: A4
Date:
Rev:
KiCad E.D.A. 10.0.0
Id: 6/10


Component Class: MOTOR_DRIVER_IC_MOTOR_DRIVER4
MOTOR_DRIVER_FETS_MOTOR_DRIVER4
VREF should be 2V if shunt is 5mOhm and we want a 20A max.
PWR_IND
C86
1u
50V
C87
22u
25V
C88
150u
35v
CAN SEE UP TO 12V
U12
C85
100n
16V
VCP
CPH
CPL
VM
GND
DRV_3V3
C82
1u
6.3V
C83
1u
6.3V
R54
47k
R55
33k
1v98
C84
1u
6.3V
DVDD
AVDD
VREF
ENABLE
PHASE
SENSEOUT
EN
PH
SO
GH1
SH1
GL1
GH2
SH2
GL2
NMOS
Q13
Q14
Q15
Q16
M4
Motor
R58
33k
nSLEEP
IDRIVE
SP
SN
R59
5m
±50ppm/C
RED-Toby
D24
D25
R56
180
R57
180
SNSOUT
nFAULT
TI DRV8701ERGER
IDrive dictates the current to the gate of mosfet, NC means 150ma source and 300ma sink.
Sheet: /MOTOR_DRIVER4/
File: MOTOR_DRIVER.kicad_sch
Title:
Size: A4
Date:
Rev:
KiCad E.D.A. 10.0.0
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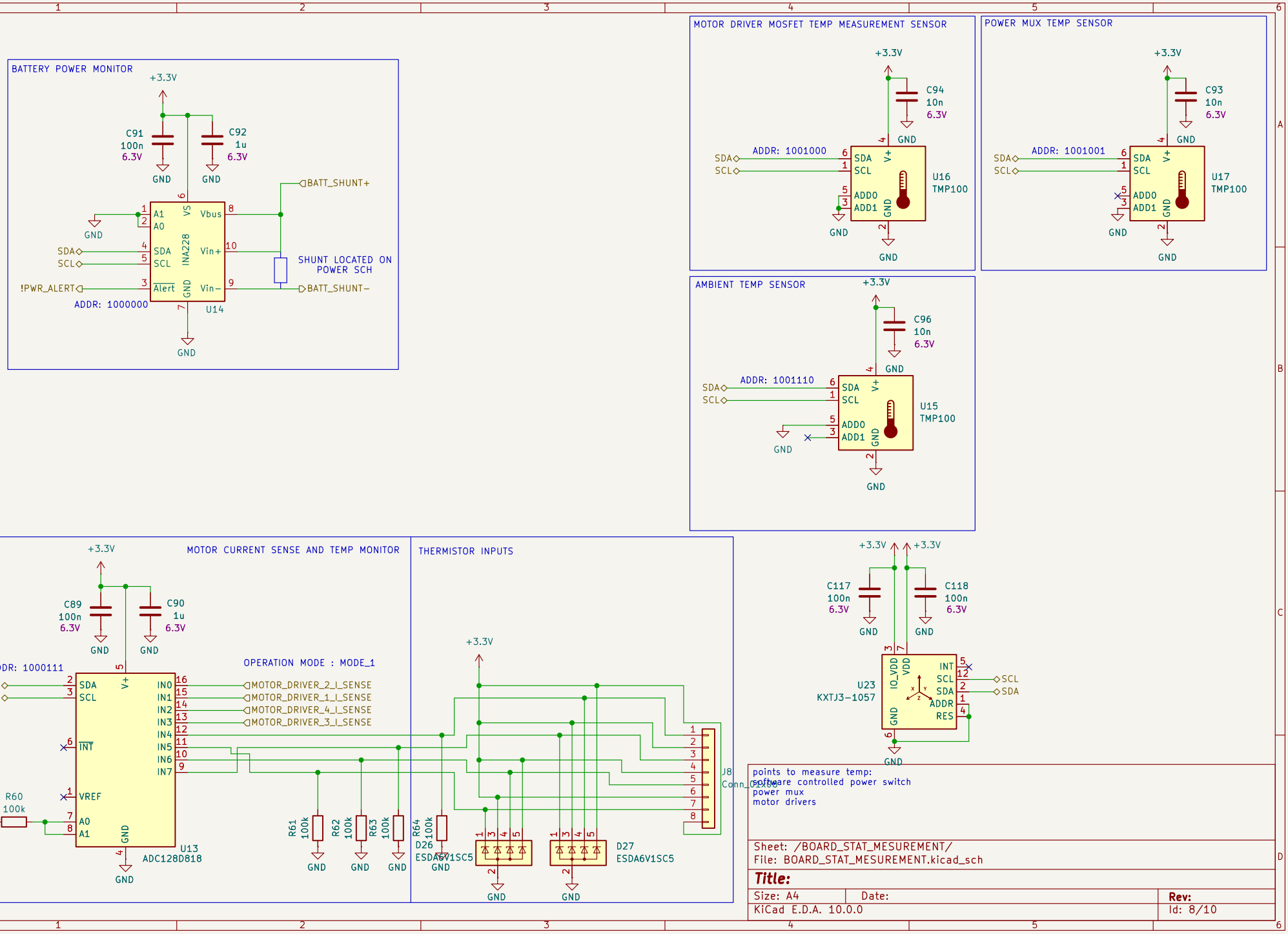
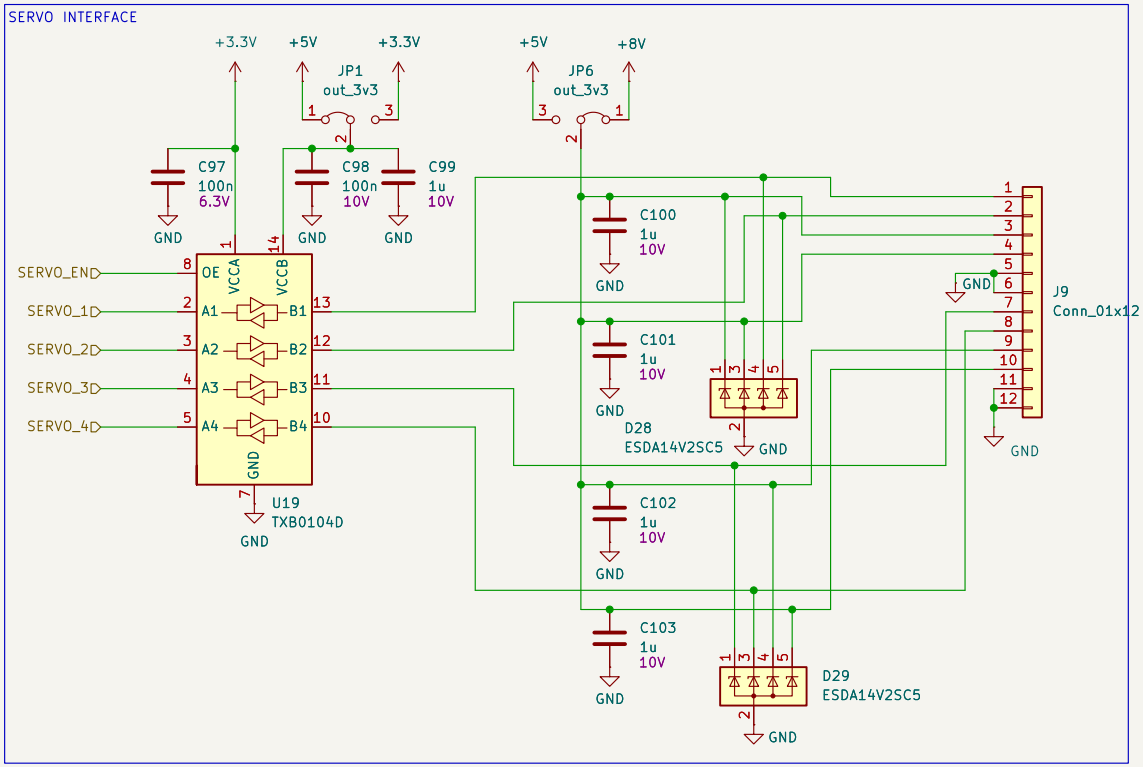
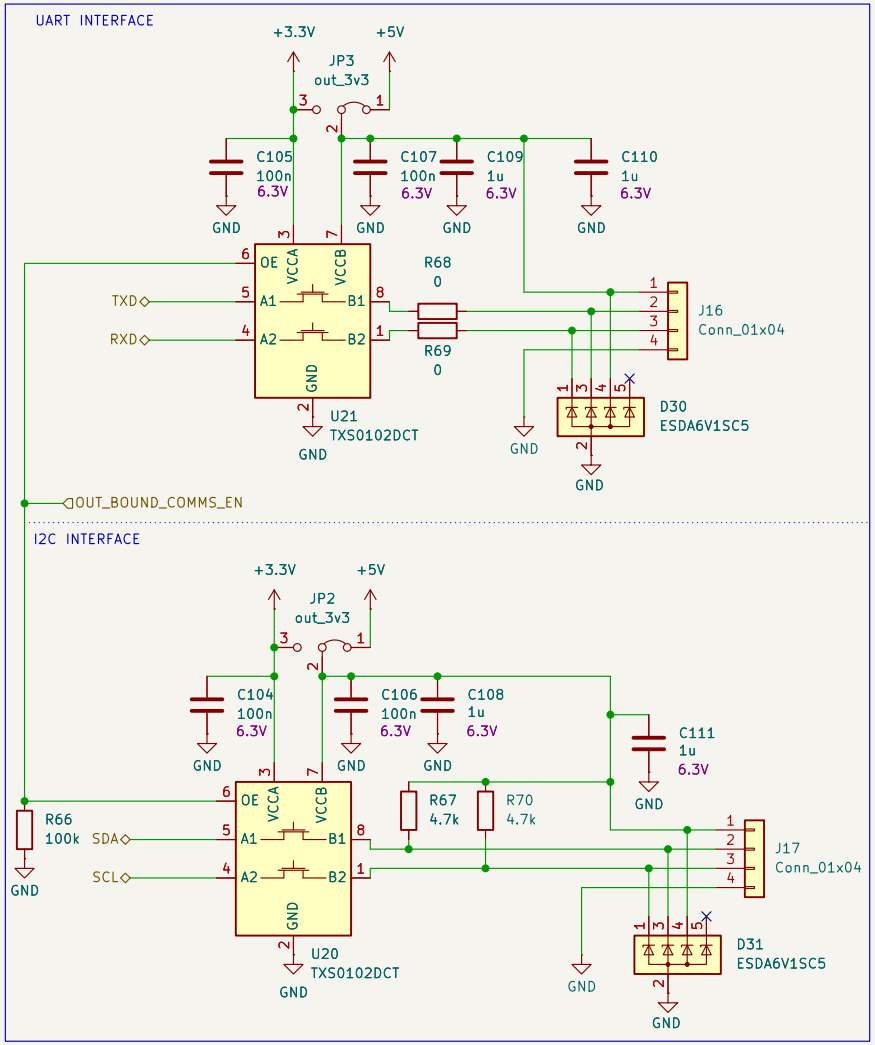

BATTERY POWER MONITOR
+3.3V
C91
100n
6.3V
C92
1u
6.3V
GND
BATT_SHUNT+
A1
A0
SDA
SCL
!PWR_ALERT
ADDR: 1000000
INA228
VS
Vbus
Vin+
Vin−
Alert
U14
SHUNT LOCATED ON
POWER SCH
BATT_SHUNT−
MOTOR DRIVER MOSFET TEMP MEASUREMENT SENSOR
C94
10n
6.3V
ADDR: 1001000
SDA
SCL
ADD0
ADD1
V+
U16
TMP100
POWER MUX TEMP SENSOR
C93
10n
6.3V
ADDR: 1001001
U17
TMP100
AMBIENT TEMP SENSOR
C96
10n
6.3V
ADDR: 1001110
U15
TMP100
MOTOR CURRENT SENSE AND TEMP MONITOR
C89
100n
6.3V
C90
1u
6.3V
ADDR: 1000111
OPERATION MODE : MODE_1
MOTOR_DRIVER_2_I_SENSE
MOTOR_DRIVER_1_I_SENSE
MOTOR_DRIVER_4_I_SENSE
MOTOR_DRIVER_3_I_SENSE
INT
VREF
R60
100k
IN0
IN1
IN2
IN3
IN4
IN5
IN6
IN7
U13
ADC128D818
THERMISTOR INPUTS
R61
100k
R62
100k
R63
100k
R64
100k
D26
ESDA6V1SC5
D27
ESDA6V1SC5
J8
Conn_01x08
C117
100n
6.3V
C118
100n
6.3V
U23
KXTJ3-1057
IO_VDD
VDD
INT
SCL
SDA
ADDR
RES
points to measure temp:
software controlled power switch
power mux
motor drivers
Sheet: /BOARD_STAT_MESUREMENT/
File: BOARD_STAT_MESUREMENT.kicad_sch
Title:
Size: A4
Date:
Rev:
KiCad E.D.A. 10.0.0
Id: 8/10





Sheet: /EXTERNAL_INTERFACING_DEVICES/
File: EXTERNAL_INTERFACING_DEVICES.kicad_sch

Title:

Size: A4	Date:	**Rev:**
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